Processes

CSE 4001 Operating Systems Concepts

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Outline



A process is a program in execution



Main components of the address space



The code part of the address space



Figure by Matt Welsh, Harvard University.

The OS view of a process

- → Process state (ready, running, blocked, ...)
- → The address space (how many possible addresses)
- → The code of the running program
- → The data of the running program
- → An execution **stack** encapsulating the state of procedure calls
- → The program counter (PC) indicating the address of the next instruction.
- → A set of general-purpose registers with current values
- → A set of operating system resources
 - open files, network connections, signals, etc.
- → CPU scheduling info: process priority
- → Each process is identified by its process ID (PID)

All these information is stored in a construct called **Process Control Block (PCB)**

The Process Control Block (PCB)

The OS maintains a PCB for each process. It is a data structure with many fields.

Defined in: /include/linux/sched.h struct task struct (volatile long state) unsigned long Flags; Execution state int sigpending: mm segment t addr limit: struct exec domain *exec domain; volatile long need resched: unsigned long ptrace; int lock depth: unsigned int cou: int prio, static prio; struct list head run list; prio array t *array: unsigned long sleep avg; unsigned long last run: unsigned long policy: unsigned long cpus allowed; unsigned int time slice, first time slice; atomic t usage: struct list head tasks; struct list head ptrace children: struct list head ptrace list: struct mm_struct mm, *active_mm; Me mory mgmt info struct linux binfmt *binfmt. int exit code, exit signal: int pdeath signal; unsigned long personality: int did exec:1: unsigned task dumpable:1; pid (pid; process ID pid t pgrp; pid t tty old pgrp; pid t session; pid t taid: int leader. struct task struct *real parent; struct task struct *parent: struct list head children; struct list head sibling; struct task struct *group leader; struct pid link pids[PIDTYPE MAX]; wait queue head t wait chldexit; struct completion *vfork done: int *set child tid; int *clear child tid: unsigned long rt priority;) Priority

unsigned long it real value, it prof value, it virt value: unsigned long it real incr, it prof incr, it wirt incr; struct timer list real timer: struct tms times; Accounting info struct tms group times: unsigned long start time: long per cou utime[NR CPUS], per cou stime[NR CPUS]; unsigned long min flt, maj flt, nswap, cmin flt, cmaj flt cnswap: int swappable:1; uid (t uid, euid, suid, fsuid; Iker ID gid t gid, egid, sgid, fsgid; int naroups: gid t groups [NGROUPS]; kernel cap t cap effective, cap inheritable, cap permitted; int keep capabilities:1: struct user struct *user; struct rlimit rlim(RLIM NLIMITS); unsigned short used math: char comm[16]; int link count, total link count; struct tty struct *tty: unsigned int locks; struct sem undo *semundo: struct sem queue *semsleeping; struct thread struct thread; CPU state struct fs struct *fs struct files_struct *files; struct namespace *namespace; Open files struct signal struct *signal: struct sighand struct *sighand; sigset t blocked, real blocked; struct sigpending pending; unsigned long sas as ap: size t sas ss size; int (*notifier) (void *priv); void *notifier data: sigset t *notifier mask: void *tux info: void (*tux exit)(void); u32 parent exec id: u32 self exec id; spinlock t alloc lock: spinlock t switch lock; void *iournal info: unsigned long ptrace message; siginfo t *last siginfo:

Figure by Matt Welsh, Harvard University.

Life cycle of a process



Figure from: OS in three easy pieces

Two processes running, no ${\rm I}/{\rm O}$



Two processes running, with ${\rm I}/{\rm O}$



Process states (Unix)



Created: Process is newly created but it is not ready to run yet.

Preempted: Process is returning from kernel to user mode, but the kernel preempts it and does a process switch to schedule another process.

Zombie: Process is no longer exists, but it leaves a record for its parent process to collect.

Figure adapted from Stallings' book

Process states (Unix) without hard drive



Process states (Unix) with hard drive



Ready queue and various I/O queue: process waiting





- OS maintains a set of queues
- Each PCB is queued on a state queue based on the process' current state.
- As processes change states, PCBs are unlinked from one queue and linked into another.

Ready queue and various ${\rm I}/{\rm O}$ queue: process moved to ready





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