

# Variable Arm Reach Extender (VARE)

## ME Capstone Project 2025-26

---

James Moore (moore2022@my.fit.edu)

**Project Manager:** Matthew Gorton (mgorton2022@my.fit.edu)

Leira Maynard (lmaynard2024@my.fit.edu)

**Systems Engineer:** Adam Johnson (adam2022@my.fit.edu)

Kaleem Bocus (kbocus2023@my.fit.edu)

**Instructor:** Dr. Anand Nellippallil (anellippallil@fit.edu)

James Koethe (jkoethe2021@my.fit.edu)

**Advisor:** Dr. Seong Hyeon Hong (shhong@fit.edu)

Quin Fredrickson (qfredrickson2020@my.fit.edu)

**GSA:** Junot Damen (jdamen2020@my.fit.edu)

Vaughn Havins (vhavins2021@my.fit.edu)

David Mierzejewski (dmierzejewski2023@my.fit.edu)

Joonhyung Si (jsi2020@my.fit.edu)

# Agenda

---

- Project goals and problem
- Project approach
- Desirable skills and knowledge

# Project Problem

---

- Roughly 20% of all disabilities in the United States are physical disabilities. With 90% of chronic disabilities relying on an assistive device for daily use.
- Within this market, a large gap has opened in assistive devices for physical disabilities.
- A significant number of assistive device users state having unmet needs ranging from 24-52% depending on the severity of their disability.

# Project Goals

---

- Design and produce a fully functional reach extender.
- Incorporate a universal end effector (grasping head) to lift a wide variety of objects.
- Restore a significant amount of physical independence to the user.
- Safely disperse the load of the object to reduce strain on the user.
- Incorporate stability controls with a strong focus on comfort and ease of use.
- Provide sensory information/ feedback to the user through various sensors and systems.

# Project Approach

---

- The intended approach is to first conduct primary research and gather information from patients and doctors on what improvements would be most beneficial.
- Use this primary research to come up with a design of both the physical structure and control systems.
- Properly code/integrate multiple different sensors and systems together into one cohesive machine.
- Conduct final testing and ensure proper functionality.

# What We Need From You

---

## Electrical Systems

- Grasping controls
- Motion controls
- Motion Tracking/ Stabilization
- External power Integration
- Human-Machine interfacing

## Sensors

- Haptic sensors
- Voltage
- Current sensor
- EM Interfacing/ sensors
- Motors
- Pressure sensors
- Location Sensors

# What We Need From You

---

## Communication

- Clear and concise communication that will demonstrate your understanding of the project
- The ability to give us a comprehensible overview of the projects script

# Interested in learning more?

---

If you are interested in learning more about this project, or would like to join the team, please refer to the contacts slide shown above!